

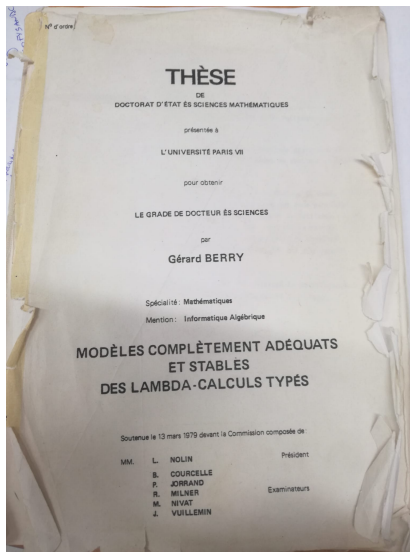
# The Philology of Strong Stability

a semi-serious tribute to Thomas Ehrhard and some other founding father

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September 29, 2022

In the beginning was a mysterious, ancient code...



...containing invaluable treasures...

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trois arguments qui est stable et  $mc$  mais n'est pas définissable [4.2.11]  
c'est la plus petite fonction continue vérifiant les trois conditions  
suivantes :

$$h(\text{vrai}, \text{faux}, 1) = \text{vrai}$$

$$h(\text{faux}, 1, \text{vrai}) = \text{vrai}$$

$$h(1, \text{vrai}, \text{faux}) = \text{vrai}$$

Nous reviendrons de façon plus précise sur la signification intuitive  
de la stabilité et de la multiplicativité sous condition à la fin du cha-  
pitre. Nous montrerons que la stabilité est en quelque sorte le "contraire"  
du parallélisme.

Nos deux conditions ne sont pas indépendantes. D'abord sur des opcd  
avec n toute fonction stable est  $mc$ [4.2.6]. De plus sur les opcd complets  
nécessaire par une condition

...but decipherable only by very few initiated (the Gustave's braves, members of a sect located on the western outskirts of Paris)...

4.3. L'ordre exponentiel sur les fonctions stables et mc.

Nous étudions les structures  $\langle [D \rightarrow E], \subset, \perp \rangle$   
 et  $\langle [D \xrightarrow{mc} E], \subset, \perp \rangle$  où  $\subset$  est l'ordre exponentiel  
 défini par  $R \subset R'$  si  $R(x) \subset R'(x)$  pour tout  $x$ .  
 Remarquons immédiatement que cet ordre n'assure pas  
 l'exponentiation dans les catégories correspondantes.

4.3.1. Contre-exemple: La fonction d'application de  
 $\langle [D \rightarrow E], \subset, \perp \rangle \times 0$  dans  $E$  (resp.  $\langle [D \xrightarrow{mc} E], \subset, \perp \rangle \times 0$   
 dans  $E$ ) n'est en général pas stable (resp. pas mc).

preuve: Il suffit de prendre  $D = E = \Phi = I$ ,  
 $R_1$  et  $R_2$  définies par  $R_1(\perp) = \perp$ ,  $R_2(T) = T$ ,  
 $R_2(\perp) = R_2(T) = T$ . Si  $\text{app}(R_1) = R(x)$ , alors  
 $m(\text{app}, R_2, T)$  n'existe pas puisque l'ensemble  
 $\{(R, x) \mid R \subset R_2, x \subset T\}$  a deux points maximaux  
 $(R_1, T)$  et  $(R_2, T)$  mais pas de point minimum. Donc  
 $\text{app}$  n'est pas stable. De même  $(R_2, T) \uparrow (R_2, \perp)$ ,  
 et  $\text{app}(R_1, T) \cap \text{app}(R_2, T) = T \neq \perp = \text{app}(R_1 \cap R_2, \perp \cap T)$ .  
 Donc  $\text{app}$  n'est pas mc.  $\square$

Nous construisons dans les paragraphes suivants  
 les ordres qui assurent l'exponentiation. Cependant l'ordre  
 de l'ordre exponentiel n'est pas sans intérêt et  
 nous revenons ensuite en 4.7.

# ...but having pierced the code, and climbed some other stormy peaks...

## NORMAL FUNCTORS, POWER SERIES AND L-CALCULUS

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Received 1993

### Introduction

This paper presents a new approach to the general subject known as 'lambda-bounded fixpoints' which includes computer-oriented topics such as models of recursive computation. It also develops directly the main features of this approach: a type in a collection of models, 'normal' if it is a type, an algebra of fixpoints, a very particular of model states. An object of type  $A$  can be viewed as a term  $\lambda x.M$ , or, when the normal  $A$  represents the model states, as the  $M$  part without the  $\lambda$  part, which can be interpreted as the substitution of such model states. So this differs from current constructions in two ways:

- (1) because we avoid configurations (instead of just considering whether a state is present);
  - (2) because we avoid compatibility between the states in required: all conditions are imposed.
- Let us not clarify that for the usual types of data, this makes a reasonable sense: expressions represent the state values of computations, and ground computations are just formal representations of these usual models. Such computations are model related to consider if they are possible: program finiteness reduces to model finiteness in the sense of getting the answer (especially in the case of the model  $\lambda$ , if we have an answer  $\lambda$  for 'Yes', then  $\lambda$  for 'No', then  $\lambda$  for 'Yes', because there are no ways to compute the value  $\lambda$ ). But also, in lambda programs, where we can consider the composition of all possible answers depending on an answer choice made during the execution, domain  $A$  which is open given its results, gives some ideas how to interpret recursive functions in this framework.

The origin of the work was in the need for some tool, however as handbooks of finite type and  $\lambda$ -fixpoints. The results of [G, Ch. 32] (in constant of interest in this connection) just for instance the remarkable work of Piperno [Pi] but more extensively, see also, Jean-Yves Girard, Jean-Louis Krivine, G.Y. (forthcoming)

## LINEAR LOGIC\*

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Communicated by M. Hahn  
Received 20 October 1993

(A la mémoire de Anne van Dalen)

**Abstract.** The familiar concepts of negation and tensor, how negation which is the dual negation of negation and the reduction of proof which has the meaning of a substitution, depending on the context, a complete new approach to the main issues concerning tensor and higher-order proof-terminability.

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\* This paper is a revised and extended version of the paper presented at the annual meeting of the European Association for Computational Logic, held in Paris, France, in 1993. The author would like to thank the anonymous referees for their helpful comments.

0168-1944/95/070129-29\$08.00/0

## SEQUENTIAL ALGORITHMS ON CONCRETE DATA STRUCTURES

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Communicated by M. Hahn  
Received 1993

**Abstract.** We describe an algorithmic model for sequential programming languages, based on a new notion of algorithmic data structure. In this model, algorithms are represented as sequences of operations on a data structure, and are executed sequentially. The model is designed to be a natural extension of the existing model of sequential programming languages, and is intended to be a natural extension of the existing model of sequential programming languages. The model is designed to be a natural extension of the existing model of sequential programming languages, and is intended to be a natural extension of the existing model of sequential programming languages.

### 1. Introduction

The term 'sequential programming language' is often used when referring to languages such as ALGOL, BASIC, LISP, etc. The usual definition of a sequential programming language is one in which the order of execution of the statements is important. In this paper, we consider a more general notion of a sequential programming language, one in which the order of execution of the statements is not important. We consider a model of sequential programming languages, based on a new notion of algorithmic data structure. In this model, algorithms are represented as sequences of operations on a data structure, and are executed sequentially. The model is designed to be a natural extension of the existing model of sequential programming languages, and is intended to be a natural extension of the existing model of sequential programming languages.

The notion of algorithmic data structure is a new notion of data structure, which is designed to be a natural extension of the existing model of sequential programming languages. The model is designed to be a natural extension of the existing model of sequential programming languages, and is intended to be a natural extension of the existing model of sequential programming languages.

## Superadditivity and Strong Stability

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### Abstract

We show that the Kahn-Powell semigroup is a natural extension of the existing model of sequential programming languages, and is intended to be a natural extension of the existing model of sequential programming languages.

### Introduction

The notion of algorithmic data structure is a new notion of data structure, which is designed to be a natural extension of the existing model of sequential programming languages. The model is designed to be a natural extension of the existing model of sequential programming languages, and is intended to be a natural extension of the existing model of sequential programming languages.

### 1. Qualitative denotational and coherence aspects

The notion of algorithmic data structure is a new notion of data structure, which is designed to be a natural extension of the existing model of sequential programming languages. The model is designed to be a natural extension of the existing model of sequential programming languages, and is intended to be a natural extension of the existing model of sequential programming languages.

0168-1944/95/070129-29\$08.00/0

## Historical introduction to 'Concrete domains' by G. Kahn and G.D. Plotkin

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The original version of this paper appeared as a technical report 17 years ago [20], based on the work of Kahn and Plotkin themselves in the Fall of 1977. The final version introduced in this work has been widely reviewed and has become the basis for a significant body of theoretical research on semantics of programming languages. The purpose of this introduction is to sketch the background for the research and to provide a brief survey of the state of the art, thus placing the paper in context.

Christopher Strachey [19] was the formal description of programming languages. He was the first to describe the semantics of a programming language for lambda. Kahn and Plotkin developed a theory of domains and continuous functions that provided a natural mathematical foundation for the subject. Their description and formalized the basis for the denotational approach to semantics, all included in [17] and later applied to a wide variety of programming languages [18, 21, 22]. However, domains were originally used to compute lambda [20] or other general kinds of complete partial orders. On the other hand, the notion of the denotational semantics being given to the lambda calculus and other theories is applied to model an abstract computation process. A good survey of domains theory is given in [14].

However, these domains themselves typically need to be made distinct between domains used to compute data and domains used to compute the denotation of functions. For certain purposes it seems appropriate to make such distinctions for

Communicated by M. Hahn. This paper is a revised and extended version of the paper presented at the annual meeting of the European Association for Computational Logic, held in Paris, France, in 1993.

0168-1944/95/070129-29\$08.00/0





## Hypercoherences: a strongly stable model of linear logic

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*Received 3 March 1992; revised 13 October 1992*

We present a new model of classical linear logic based on the notion of *strong stability* that was introduced recently in a work about sequentality written jointly with Antonio Bucciarelli.

### 1. Introduction

In the denotational semantics of purely functional languages (such as PCF (Plotkin 1977; Berry *et al.* 1985)), types are interpreted as objects and programs as morphisms in a cartesian closed category (CCC for short). Usually, the objects of this category are at least Scott domains, and the morphisms are at least continuous functions. One carefully avoids making any reference to the syntax of the language in defining such a model; the goal of semantics is to express precisely, and in a “purely abstract way”, some interesting properties of the language.

One of these properties is “continuity”. It corresponds to the basic fact that any computation that terminates can use only a finite amount of data. The corresponding semantics of PCF is the continuous one, where objects are Scott domains, and morphisms are continuous functions.

But the continuous semantics does not capture an important property of computations in PCF, namely “determinism”. It is much harder to model abstractly the idea of determinism. Vuillemin and Milner produced the first (equivalent) definitions of sequentality. Kahn and Plotkin (1978) generalized this notion of sequentality. More precisely, they defined a category of “concrete domains” (represented by “concrete data structures”) and of sequential functions.

We shall begin with an intuitive description of what sequentality is, in the framework of concrete data structures (CDS's). A CDS  $D$ , very roughly, is a Scott domain equipped with a notion of “places” or “cells”. An element of  $D$  is a partial piece of data, where some cells are filled, and others are not. A cell can be filled, in general, by different values. (Think of the cartesian product of two ground types: there are two cells corresponding to the two places one can fill in a couple.) In a CDS, an element  $x$  is less than an element



# Stability and sequentiality: one very same pattern

	stability	sequentiality
“Circumstantiated”	dl-domains and stable functions	Concrete domains and sequential functions Concrete data structures and sequential algorithms
Algebraic	Qualitative domains and cm functions	QD with coherence and strongly stable functions
Linear	Coherence spaces	Hypercoherences

Thank you all, and cheers, Thomas!